

CMSC 28100

Introduction to
Complexity Theory

Spring 2024

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Asymptotic analysis

Big- O , big- Ω , and big- Θ

- Let $T, f: \mathbb{N} \rightarrow \mathbb{N}$ be any two functions
- We say that T is $O(f)$ if there exist $C, n_* \in \mathbb{N}$ such that for every $n > n_*$, we have $T(n) \leq C \cdot f(n)$
- We say that T is $\Omega(f)$ if there exist $c \in (0, 1)$ and $n_* \in \mathbb{N}$ such that for every $n > n_*$, we have $T(n) \geq c \cdot f(n)$
- We say that T is $\Theta(f)$ if T is both $O(f)$ and $\Omega(f)$ simultaneously

Little- o notation

- Let $T, f: \mathbb{N} \rightarrow \mathbb{N}$ be any two functions
- We say that T is $o(f)$ if for every $c \in (0, 1)$, there exists $n_* \in \mathbb{N}$ such that for every $n > n_*$, we have $T(n) < c \cdot f(n)$
- Equivalent:

$$\lim_{n \rightarrow \infty} \frac{T(n)}{f(n)} = 0$$

Little- ω notation

- Let $T, f: \mathbb{N} \rightarrow \mathbb{N}$ be any two functions
- We say that T is $\omega(f)$ if for every $C \in \mathbb{N}$, there exists $n_* \in \mathbb{N}$ such that for every $n > n_*$, we have $T(n) > C \cdot f(n)$
- Equivalent:

$$\lim_{n \rightarrow \infty} \frac{T(n)}{f(n)} = \infty$$

Summary of asymptotic notation

Notation	In words	Analogy
T is $o(f)$	$T(n)$ grows more slowly than $f(n)$	$<$
T is $O(f)$	$T(n)$ is at most $C \cdot f(n)$	\leq
T is $\Theta(f)$	$T(n)$ and $f(n)$ grow at the same rate	$=$
T is $\Omega(f)$	$T(n)$ is at least $c \cdot f(n)$	\geq
T is $\omega(f)$	$T(n)$ grows more quickly than $f(n)$	$>$

Note: Big- O is not just for time complexity!

- We can use asymptotic notation (big- O , etc.) any time we are trying to understand some kind of “scaling behavior”
- For example, let G be a simple undirected graph with N vertices
 - G has $O(N^2)$ edges
 - If G is connected, then G has $\Omega(N)$ edges
- Admittedly, we are especially interested in time complexity...

Exponential vs. polynomial

- We are especially interested in the distinction between a **polynomial** time complexity, such as $T(n) = n^2$, and an **exponential** time complexity, such as $T(n) = 2^n$
- We write $T(n) = \mathbf{poly}(n)$ if there is some k such that $T(n) = O(n^k)$
- Exponentials grow much faster than polynomials!

Exponential vs. polynomial

Claim: For every constant $k \in \mathbb{N}$, we have $n^k = o(2^n)$

- **Proof:** If $n \geq k$, then

$$2^n = \# \text{ subsets of } \{1, 2, \dots, n\} = \sum_{i=0}^n \binom{n}{i} \geq \binom{n}{k} \geq \left(\frac{n}{k}\right)^k$$

- Therefore, for every k , we have $2^n = \Omega(n^k)$
- Therefore, for every k , we have $2^n = \Omega(n^{k+1}) = \omega(n^k)$

Which problems
can be **solved**
through computation?

The complexity class P

- **Definition:** For any function $T: \mathbb{N} \rightarrow \mathbb{N}$, we let $\text{TIME}(T)$ denote the class of all languages that can be decided in time $O(T)$
- **Definition:** We let P denote the class of all languages that can be decided in time $\text{poly}(n)$, i.e., in polynomial time

$$P = \bigcup_{k=1}^{\infty} \text{TIME}(n^k)$$

P: Our model of tractability

- Let L be a language
- If $L \in P$, then we will consider L “tractable”
- If $L \notin P$, then we will consider L “intractable”

Example: Primality testing

- PRIMES = $\{\langle N \rangle : N \text{ is a prime number}\}$

Theorem: PRIMES \in P

- **Proof attempt:** For $M = 2, 3, \dots, N - 1$, check if N/M is an integer.
- That proof is **not correct**. The algorithm runs in **poly(N)** time, but our time budget is only **poly(n)** where $n = |\langle N \rangle| \approx \log N!$
- The theorem is true, but the proof is beyond the scope of this course

Example: Decompositions into squares

- We designed an algorithm that decides DECOMPOSABLE-INTO-SQUARES
- That algorithm's time complexity is $\Omega(2^n)$
- Can we conclude that DECOMPOSABLE-INTO-SQUARES \notin P?

Theorem: DECOMPOSABLE-INTO-SQUARES \in P

Decomposing into squares in polynomial time

Theorem: DECOMPOSABLE-INTO-SQUARES $\in P$

- **Proof:** We'll use an algorithm technique called “dynamic programming”
- Key observation: A nonempty string $w \in \{0, 1\}^*$ can be decomposed into squares **if and only if** it can be written in the form $w = uy$, where u can be decomposed into squares, $|u| < |w|$, and $y \in \text{SQUARES}$

Decomposing into squares in polynomial time

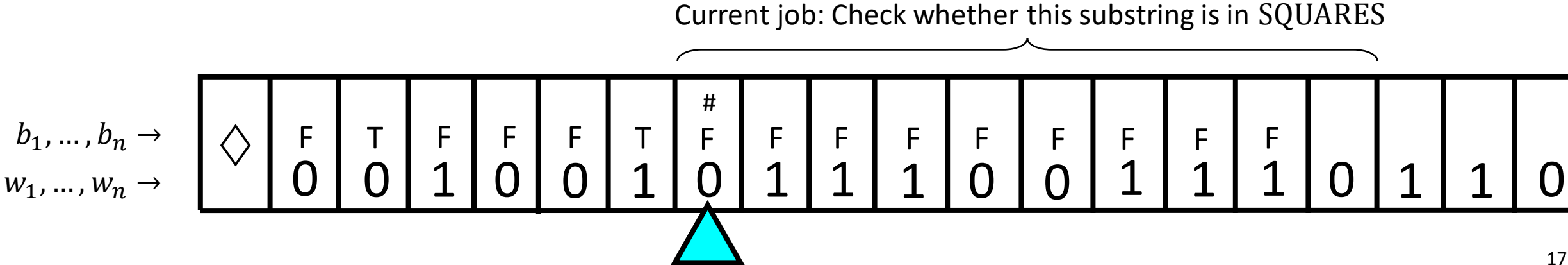
- Let w be the input, $w = w_1 w_2 \dots w_n$, where $w_i \in \{0, 1\}$
- Plan: For each $i \in \{0, 1, \dots, n\}$, we will compute a Boolean value b_i that indicates whether $w_1 w_2 \dots w_i \in \text{DECOMPOSABLE-INTO-SQUARES}$

<p>1) Let $b_0 = \text{True}$</p> <p>2) For $i = 1$ to n</p> <p> a) If there exists $j < i$ such that $w_j = 0$</p> <p> b) Otherwise</p> <p>3) Accept if b_n is</p>	<p>What should b_0 be?</p> <p>A: True B: False</p> <p>C: It depends on w D: It's not well-defined</p> <p>Respond at PollEv.com/whoza or text "whoza" to 22333</p>	<p>= True</p>
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Decomposing into squares in polynomial time

- 1) Let $b_0 = \text{True}$
- 2) For $i = 1$ to n :
 - a) If there exists $j < i$ such that b_{j-1} is True and $w_j \dots w_i \in \text{SQUARES}$, then set $b_i = \text{True}$
 - b) Otherwise, set $b_i = \text{False}$
- 3) Accept if b_n is True; reject if b_n is False

- TM implementation: Store b_i in w_i 's cell, and write # in w_j 's cell



Decomposing into squares in polynomial time

- 1) Let $b_0 = \text{True}$
- 2) For $i = 1$ to n :
 - a) If there exists $j < i$ such that b_{j-1} is True and $w_j \dots w_i \in \text{SQUARES}$, then set $b_i = \text{True}$
 - b) Otherwise, set $b_i = \text{False}$
- 3) Accept if b_n is True; reject if b_n is False

- Outer loop (i) does $O(n)$ iterations; inner loop (j) does $O(n)$ iterations
- We can check whether $w_j \dots w_i \in \text{SQUARES}$ in time $O(n^2)$
- Total time complexity: $O(n^4) = \text{poly}(n)$ ✓

Time complexity: Theory vs. practice

- **OBJECTION:** “In an **algorithms** course, or in the computing **industry**, we would say that we can decide SQUARES in time $O(n)$ rather than $O(n^2)$.”

Given an array of bits y :

1) For $i = 1$ to $n/2$:

← $O(n)$ iterations

a) If $y[i] \neq y[i + n/2]$, reject

← $O(1)$ time per iteration “in practice”

2) Accept

- Is there something wrong with the Turing machine model?

Time complexity: Theory vs. practice

- **RESPONSE:** In this course, we are not concerned about the distinction between $O(n)$ time and $O(n^2)$ time
- The Turing machine model is arguably inappropriate for studying **fine-grained** time complexity... but that's not our mission
- We are trying to understand the boundary between **tractable** and **intractable**. **Feasible** vs. **infeasible**.
- Is the algorithm **usable**, or is it so slow that it's practically **worthless**?

Is the Turing machine model a good model?

- Switching between **two reasonable models** of computation can sometimes make the difference between **linear** time and **quadratic** time
- Could it ever make the difference between **polynomial** time and **exponential** time?
- For example, what happens if we use a **multi-tape** Turing machine instead of a single-tape Turing machine?

Multi-tape Turing machines, revisited

- Let L be a language, let k be a positive integer, and let $T: \mathbb{N} \rightarrow \mathbb{N}$

Theorem: If there is a k -tape Turing machine that decides L with time complexity T , then there is a 1-tape Turing machine that decides L with time complexity $O(T^2 + T \cdot n)$.

- Note: If $T(n) = O(n^k)$, then $O(T^2 + T \cdot n) = O(n^{2k}) = \text{poly}(n)$

Efficiently simulating k tapes using one tape

- **Proof sketch:** Let M be the k -tape Turing machine deciding L
- Recall our simulation of M by a one-tape machine...
- To simulate step i , we scan back and forth over $n + i$ cells of the tape
- Therefore, simulating **one** step of M takes $O(n + T(n))$ steps
- Overall time complexity: $T(n) \cdot O(n + T(n))$

Robustness of P

- Conclusion: We could define P using one-tape Turing machines or using multi-tape Turing machines
- Either way, we get **the exact same set of languages**

Robustness of P

- Similarly, many other “realistic” models of computation can be simulated by one-tape Turing machines with at most a polynomial slowdown
 - TMs with two-way-infinite tapes
 - TMs with two-dimensional tape
 - TMs that can “teleport” to a specified location on their tape in a single step
- The complexity class P is extremely **robust** against modifications to the model of computation

Note on standards of rigor

- Going forward, when we analyze **specific** algorithms, we will not actually **prove** that they run in polynomial time... we will just assert it
 - In each case, one **can** rigorously prove the time bound by describing a TM implementation and reasoning about the motions of the heads... but this is tedious
 - Note: We still insist on proofs of **correctness**, just not efficiency
- You should follow this convention on **problem set 5** and beyond
- Nevertheless, the Turing machine model remains extremely valuable for us, because it tells us what an **arbitrary** poly-time algorithm looks like!